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The book is written for an undergraduate course on the theory of Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The book also introduces the concept of discrete time systems including digital and sample data systems, z-transform, difference equations, state space representation, pulse transfer functions and stability of linear discrete time systems. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The book is written for an undergraduate course on the Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus, the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

Non-linear stochastic systems are at the center of many engineering disciplines and progress in theoretical research had led to a better understanding of non-linear phenomena. This book provides information on new fundamental results and their applications which are beginning to appear across the entire spectrum of mechanics. The outstanding points of these proceedings are Coherent compendium of the current state of modelling and analysis of non-linear stochastic systems from engineering, applied mathematics and physics point of view. Subject areas include: Multiscale phenomena, stability and bifurcations, control and estimation, computational methods and modelling. For the Engineering and Physics communities, this book will provide first-hand information on recent mathematical developments. The applied mathematics community will benefit from the modelling and information on various possible applications.

This book gathers selected papers from two important conferences held on October 24 – 28, 2018, in Warsaw, Poland: theFifteenth National Conference of Operational and Systems Research, BOS-2018, one of the leading conferences in the field of operational and systems research not only in Poland but also at the European level; andthe Seventeenth International Workshop on Intuitionistic Fuzzy Sets and General Nets, IWIFSGN-2018, one of thepremiere conferences on fuzzy logic. The papers presented here constitute a fair and comprehensive representation of the topics covered by both BOS-2018 and IWIFSGN-2018, includingextensions of the traditional fuzzy sets, in particular on the intuitionistic fuzzy sets, as well as other topics in uncertainty and imprecision modeling, the Generalized Nets (GNs), a powerful extension of the traditional Petri net paradigm, and InterCriteria Analysis, a new method for feature selection and analyses in multicriteria and multi-attribute decision-making problems. The Workshop was dedicated to the memory of Professor Beloslav Rie an (1936 – 2018), a regular participant at the IWIFSGN workshops.

Hardbound. This volume presents state-of-the-art reports on the theory, and current and future applications of control of distributed parameter systems. The papers cover the progress not only in traditional methodology and pure research in control theory, but also the rapid growth of its importance for different applications. This title will be of interest to researchers working in the areas of mathematics, automatic control, computer science and engineering.

This book gathers selected research papers presented at the International Conference on Power, Control and Communication Infrastructure 2019 (ICPCCI 2019), organized by the Institute of Infrastructure, Technology, Research and Management (IITRAM), Ahmedabad, Gujarat, India, on July 4 – 5, 2019. It presents the latest advances, trends and challenges in control system technologies and infrastructures. The book addresses a range of solutions to the problems faced

by engineers and researchers to design and develop controllers for emerging areas like smart grid, integration of renewable energy, automated highway systems, haptics, unmanned aerial vehicles, sensor networks, robotics, formation control and many more. The solutions discussed in this book encourage and inspire researchers, industry professionals and policymakers to put these methods into practice.

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