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Striking a balance between theory and applications, Linear  
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This book is the result of our teaching over the years an undergraduate course on Linear Optimal Systems to applied mathematicians and a first-year graduate course on Linear Systems to engineers. The contents of the book bear the strong influence of the great advances in the field and of its enormous literature. However, we made no attempt to have a complete coverage. Our motivation was to write a book on linear systems that covers finite dimensional linear systems, always keeping in mind the main purpose of engineering and applied science, which is to analyze, design, and improve the performance of physical systems. Hence we discuss the effect of small nonlinearities, and of perturbations of feedback. It is our hope that the book will be a useful reference for a first-year graduate student. We assume that a typical reader with an engineering background will have gone through the conventional undergraduate single-input single-output linear systems course; an elementary course in control

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is not indispensable but may be useful for motivation. For readers from a mathematical curriculum we require only familiarity with techniques of linear algebra and of ordinary differential equations.

An extensive revision of the author's highly successful text, this third edition of Linear System Theory and Design has been made more accessible to students from all related backgrounds. After introducing the fundamental properties of linear systems, the text discusses design using state equations and transfer functions. In state-space design, Lyapunov equations are used extensively to design state feedback and state estimators. In the discussion of transfer-function design, pole placement, model matching, and their applications in tracking and disturbance rejection are covered. Both one-and two-degree-of-freedom configurations are used. All designs can be accomplished by solving sets of linear algebraic equations. The two main objectives of the text are to: 1. use simple and efficient methods to develop results and design procedures 2. enable students to employ the results to carry out design All results in this new edition are developed for numerical computation and illustrated using MATLAB, with an emphasis on the ideas behind the computation and interpretation of results. This book develops all theorems and results in a logical way so that readers can gain an intuitive understanding of the theorems. This revised edition begins with the time-invariant case and extends through the time-varying case. It also starts with single-input single-output design and extends to multi-input multi-output design. Striking a balance between theory and applications, Linear System Theory and Design, 3/e, is ideal for use in advanced undergraduate/first-year graduate courses in linear systems and multivariable system design in electrical, mechanical, chemical, and aeronautical engineering departments. It

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assumes a working knowledge of linear algebra and the Laplace transform and an elementary knowledge of differential equations.

Includes MATLAB-based computational and design algorithms utilizing the "Linear Systems Toolkit." All results and case studies presented in both the continuous- and discrete-time settings.

"Linear System Theory and Design is for use in advanced undergraduate/first-year graduate courses in linear systems and multivariable system design in electrical, mechanical, chemical, and aeronautical engineering departments"-- Provided by publisher.

This book discusses analysis and design techniques for linear feedback control systems using MATLAB® software. By reducing the mathematics, increasing MATLAB working examples, and inserting short scripts and plots within the text, the authors have created a resource suitable for almost any type of user. The book begins with a summary of the properties of linear systems and addresses modeling and model reduction issues. In the subsequent chapters on analysis, the authors introduce time domain, complex plane, and frequency domain techniques. Their coverage of design includes discussions on model-based controller designs, PID controllers, and robust control designs. A unique aspect of the book is its inclusion of a chapter on fractional-order controllers, which are useful in control engineering practice.

This text introduces the time, frequency, and transform domains in studying signals and systems and discusses their



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roles in signal processing and system design. It compares the four mathematical descriptions for the systems studied and explains why the same equation can be used to design seismometers and accelerometers.

Based on a streamlined presentation of the authors' successful work *Linear Systems*, this textbook provides an introduction to systems theory with an emphasis on control. Initial chapters present necessary mathematical background material for a fundamental understanding of the dynamical behavior of systems. Each chapter includes helpful chapter descriptions and guidelines for the reader, as well as summaries, notes, references, and exercises at the end. The emphasis throughout is on time-invariant systems, both continuous- and discrete-time.

Recent years have seen a significant rise of interest in max-linear theory and techniques. Specialised international conferences and seminars or special sessions devoted to max-algebra have been organised. This book aims to provide a first detailed and self-contained account of linear-algebraic aspects of max-algebra for general (that is both irreducible and reducible) matrices. Among the main features of the book is the presentation of the fundamental max-algebraic theory (Chapters 1-4), often scattered in research articles, reports and theses, in one place in a comprehensive and unified form. This presentation is made with all proofs and in full generality (that is for both irreducible and reducible matrices). Another feature is the presence of advanced material (Chapters 5-10), most of which has not appeared in a book before and in many cases has not been published at all. Intended for a wide-ranging readership, this book will be useful for anyone with basic mathematical knowledge (including undergraduate students) who wish to learn

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fundamental max-algebraic ideas and techniques. It will also be useful for researchers working in tropical geometry or idempotent analysis.

"There are three words that characterize this work: thoroughness, completeness and clarity. The authors are congratulated for taking the time to write an excellent linear systems textbook!" —IEEE Transactions on Automatic Control

Linear systems theory plays a broad and fundamental role in electrical, mechanical, chemical and aerospace engineering, communications, and signal processing. A thorough introduction to systems theory with emphasis on control is presented in this self-contained textbook, written for a challenging one-semester graduate course. A solutions manual is available to instructors upon adoption of the text. The book's flexible coverage and self-contained presentation also make it an excellent reference guide or self-study manual. For a treatment of linear systems that focuses primarily on the time-invariant case using streamlined presentation of the material with less formal and more intuitive proofs, please see the authors' companion book entitled *A Linear Systems Primer*.

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