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Toyota Innova is available with both petrol and diesel engine options ... of maximum torque at 4000rpm. The diesel variants of the car are available with a 2.5-litre, 2494cc, 2KD-FTV, Turbocharged ...

~~Tell me the engine specifications of Toyota Innova?~~

Toyota Innova comes with two engine options; the diesel variants come equipped with a 2KD-FTV D4-D 2.5-litre ... ratio is according to power output and torque. On the other hand, the petrol ...

This book comprises the select proceedings of the International

Conference on Power Engineering Computing and Control (PECCON) 2019. This volume focuses on the different renewable energy sources which are integrated in a smart grid and their operation both in the grid connected mode and islanded mode. The contents highlight the role of power converters in the smart grid environment, battery management, electric vehicular technology and electric charging station as a load for the power network. This book can be useful for beginners, researchers as well as professionals interested in the area of smart grid technology.

A timely introduction to current research on PID and predictive control by one of the leading authors on the subject PID and Predictive Control of Electric Drives and Power Supplies using MATLAB/Simulink examines the classical control system strategies, such as PID control, feed-forward control and cascade control, which are widely used in current practice. The authors share their experiences in actual design and implementation of the control systems on laboratory test-beds, taking the reader from the fundamentals through to more sophisticated design and analysis. The book contains sections on closed-loop performance analysis in both frequency domain and time domain, presented to help the designer in selection of controller parameters and validation of the control system. Continuous-time model predictive control systems are designed for the drives and power supplies, and operational constraints are imposed in the design. Discrete-time model predictive control systems are designed based on the discretization of the physical models, which will appeal to readers who are more familiar with sampled-data control system. Soft sensors and observers will be discussed for low cost implementation. Resonant control of the electric drives and power supply will be discussed to deal with the problems of bias in sensors and unbalanced three phase AC currents. Brings together both classical control systems and predictive control systems in a logical style from introductory through to advanced levels Demonstrates how simulation and experimental results are used to support theoretical analysis and the proposed design algorithms MATLAB and Simulink tutorials are given in each chapter to show the readers how to take the theory to applications. Includes MATLAB and Simulink software using xPC Target for teaching purposes A companion website is available Researchers and industrial engineers; and graduate students on electrical engineering courses will find this a valuable resource.

The light-duty vehicle fleet is expected to undergo substantial technological changes over the next several decades. New powertrain designs, alternative fuels, advanced materials and significant changes to the vehicle body are being driven by increasingly stringent fuel economy and greenhouse gas emission standards. By the end of the next decade, cars and light-duty trucks will be more fuel efficient, weigh less, emit less air pollutants, have more safety features, and will be more expensive to purchase relative to current vehicles. Though the gasoline-powered spark ignition engine will continue to be the

dominant powertrain configuration even through 2030, such vehicles will be equipped with advanced technologies, materials, electronics and controls, and aerodynamics. And by 2030, the deployment of alternative methods to propel and fuel vehicles and alternative modes of transportation, including autonomous vehicles, will be well underway. What are these new technologies - how will they work, and will some technologies be more effective than others? Written to inform The United States Department of Transportation's National Highway Traffic Safety Administration (NHTSA) and Environmental Protection Agency (EPA) Corporate Average Fuel Economy (CAFE) and greenhouse gas (GHG) emission standards, this new report from the National Research Council is a technical evaluation of costs, benefits, and implementation issues of fuel reduction technologies for next-generation light-duty vehicles. Cost, Effectiveness, and Deployment of Fuel Economy Technologies for Light-Duty Vehicles estimates the cost, potential efficiency improvements, and barriers to commercial deployment of technologies that might be employed from 2020 to 2030. This report describes these promising technologies and makes recommendations for their inclusion on the list of technologies applicable for the 2017-2025 CAFE standards.

This book covers recent trends in the field of devices, wireless communication and networking. It gathers selected papers presented at the International Conference on Communication, Devices and Networking (ICCDN 2019), which was organized by the Department of Electronics and Communication Engineering, Sikkim Manipal Institute of Technology, Sikkim, India, on 9-10 December 2019. Gathering cutting-edge research papers prepared by researchers, engineers and industry professionals, it will help young and experienced scientists and developers alike to explore new perspectives, and offer them inspirations on how to address real-world problems in the areas of electronics, communication, devices and networking.

When the war ended on August IS, 1945, I was a naval engineering cadet at the Kure Navy Yard near Hiroshima, Japan. A week later, I was demobi lized and returned to my home in Tokyo, fortunate not to find it ravaged by firebombing. At the beginning of September, a large contingent of the Ameri can occupation forces led by General Douglas MacArthur moved its base from Yokohama to Tokyo. Near my home I watched a procession of American mili tary motor vehicles snaking along Highway 1. This truly awe-inspiring cavalcade included jeeps, two-and-a-half-ton trucks, and enormous trailers mounted with tanks and artillery. At the time, I was a 21-year-old student in the Machinery Section of Engineering at the Tokyo Imperial University. Watching that mag nificent parade of military vehicles, I was more than impressed by the gap in industrial strength between Japan and the U. S. That realization led me to devote my whole life to the development of the Japanese auto industry. I wrote a small article concerning this incident in Nikkei Sangyo Shimbun (one of the leading business newspapers in Japan) on May 2, 1983. The English translation

of this story was carried in the July 3, 1983 edition of the Topeka Capital-Journal and the September 13, 1983 issue of the Asian Wall Street Journal. The Topeka Capital-Journal headline read, "MacArthur's Jeeps Were the Toyota Catalyst.

We cannot imagine a world without plastics. Plastic products make our daily life safe, healthy and convenient. Besides all the benefits, the current plastics economy gives rise to environmental concerns with respect to fossil oil depletion and plastic waste accumulation. In a circular economy, however, plastics can be redesigned for reusability and recyclability. This book makes the topic of sustainable plastics approachable for students and career starters alike, describing the nature and chemistry of (bio)polymers as well as how to create a closed loop of plastic materials.

This book constitutes the refereed proceedings of the 4th International Conference on Interactive Collaborative Robotics, ICR 2019, held in Istanbul, Turkey, in August 2019. The 32 papers presented in this volume were carefully reviewed and selected from 46 submissions. They deal with challenges of human-robot interaction; robot control and behavior in social robotics and collaborative robotics; and applied robotic and cyber-physical systems.

The international conference on "Pedestrian and Evacuation Dynamics", held on February 27-29, 2008 at Wuppertal University in Germany, was the fourth in this series after successful meetings in Duisburg (2001), Greenwich (2003) and Vienna (2005). The conference was aimed at improving the scientific exchange between scientists, experts and practitioners of various fields of pedestrian and evacuation dynamics and featured: the analysis of evacuation processes and pedestrian motion, modeling of pedestrian dynamics in various situations, experiments on pedestrian dynamics, human behavior research, regulatory action. All these topics are included in this book to give a broad and state-of-the-art overview of pedestrian and evacuation dynamics.